**Standard Supervision Plan for Thesis**

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| Study programme | MSc in Engineering (Robot Systems) |
| Semester/Year | Autumn/2021 - Spring/2022 |

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| **Student** | |
| Name | Nathan Durocher |
| SDU mail | [Nadur20@student.sdu.dk](mailto:Nadur20@student.sdu.dk) |
| Fellow students, if relevant | - |

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| Subjects/list of references before writing the thesis | May 30, 2021 |
| Registration for course | May 30, 2021 |
| Appointment with supervisor | June 24, 2021 |
| Contract approved by the Head of Studies | August 31, 2021 |

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| Name of supervisor | Leon Bodenhagen |
| Project title | Autonomous Urban Environment Navigation Using Reinforcement Learning |

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| **Subjects/list of references in connection with supervision** | **Completed Date:** |
| Agreed form of and time for meetings with supervisor | September 10, 2021 |
| Problem formulation made and discussed with supervisor | September 30, 2021 |
| Preliminary choice of source literature | September 30, 2021 |
| (if relevant) Choice of methodology | September 30, 2021 |
| (if relevant) Plan for the experimental part drawn up | April 15, 2022 |
| Final choice of source literature | May 15, 2022 |
| Compulsory meeting 1 month prior to completion date | April 29, 2022 |

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| The Supervision Plan will be kept by the student with a copy for the supervisor.  The Supervision Plan is handed in with the project. |